

NOTATIONS

A	Cross sectional area of member
a, b	Size of plate
\mathbf{a}^n	Displacement vector in n^{th} iteration
$[B]$	Strain – displacement relation matrix
C	Violation coefficient
c_x, c_y, c_z	Direction cosine of member w.r.t. X, Y and Z axis
$[D]$	Constitutive law matrix
$\{d\}$	Displacement vector
E	Young's modulus of elasticity
E_1, E_2, E_3	Modulus of elasticity in three directions
f	Natural frequency
G_{12}, G_{23}, G_{13}	Modulus of rigidity in three directions
h	Thickness of plate
$[I]$	Unit matrix
I	Moment of inertia of a member
$ J $	Determinant of Jacobian matrix
$[K], [k], \mathbf{K}$	Stiffness matrix
\mathbf{K}_T^n	Tangential stiffness matrix in n^{th} iteration
K_x, K_y, K_{xy}	Curvatures
L	Length of member
$[M]$	Mass matrix
M_x, M_y, M_{xy}	Moment about x and y axis and torsional moment
$[N]$	Shape functions
$\{Q\}, \{q\}$	Load vector
Q_x, Q_y	Shear forces
Q_0	Uniformly distributed transverse load
$[R]$	Rotation transformation matrix
R	Radius
S	Surface force
$[T]$	Transformation matrix

T	Time period
T_x, T_y, T_{xy}	Membrane forces
u, v, w	Displacements in x. y and z direction respectively
u_a	Allowable displacement
u_j	Displacement of a joint
W_a and W_b	Weight at Gauss points
(x_j, y_j)	Coordinates of a joint
$[Y]$	Degrees of freedom
z	Distance from mid plane of plate
$\Delta\alpha^n$	Correction in displacement vector in n^{th} iteration
$\epsilon_x, \epsilon_y, \epsilon_z$	Normal strains
(ξ, η)	Natural coordinates
$\phi(x)$	Unconstrained / modified objective function
ϕ_x, ϕ_y	Shear deformations
$\gamma_{xy}, \gamma_{yz}, \gamma_{zx}$	Shear strains
ν	Poisson's ratio
$\nu_{21}, \nu_{32}, \nu_{31}$	Poisson's ratio in three directions
θ_x, θ_y	Rotation about x and y axes
ρ	Density of material
σ_a	Allowable stress
σ_i	Stress in a member
σ_θ	Radial stress
$\sigma_x, \sigma_y, \sigma_z$	Normal stresses
$\tau_{xy}, \tau_{yz}, \tau_{zx}$	Shear stresses
ω	Circular natural frequency
ψ	Unbalanced force vector