

Table of Contents

Chapter No.	Title	Page No.
	List of Figures	xi
	List of Tables	xiv
	Abstract	xv
1	Introduction	1
	1.1 Introduction	2
	1.2 Direct Warping	2
	1.3 Sectional Warping	3
	1.4 Objectives of the Work	5
2	Literature Review	7
	2.1 General	8
	2.2 Effect of Process Control Parameters	9
	2.2.1 Quality of Beam	9
	2.2.2 Objectives for Designing Beam for Direct Warper	13
	2.2.3 Objectives for Designing Beam for Sectional Warper	15
	2.2.4 Yarn Stresses on a Beam	16
	2.2.5 Problems of Running Smaller Lots	17
	2.2.6 Problems of Calculating Movement for Sectional Warping	18
	2.3 Patents	19
	2.3.1 Modifications in the Creel	19
	2.3.1.1 Circular Creel	20
	2.3.1.2 Automatic switching of threads in creel	22

	2.3.2 Modifications of the beam flanges	23
	2.3.2.1 Use of metal sleeve	23
	2.3.2.2 Modifications based on smaller beams	27
	2.3.2.3 Flange with metal and coating	28
	2.3.2.4 Conical shaped flange	30
	2.3.2.5 Patent about width adjustment of weaver's beam	32
	2.3.3 Sections in the beam	33
	2.3.3.1 Early Version of Sectional Warping	33
	2.3.3.2 Patents about Setting Warp on Beam	34
	2.3.3.3 Problems with beams to be used for multi width working	36
	2.3.3.4 Using narrow width beams for normal yarns	37
	2.3.3.5 Using narrow width beams for specialty yarns	39
	2.3.3.6 Producing two beams from one sectional warping drum	41
	2.3.3.7 Section Beams with Separator Plates	42
	2.3.4 Beams with Adjustable Sections	42
	2.3.4.1 Multiple beamer for Raschel Knitting with width adjustment	43
	2.3.4.2 Double Warp beam Warper	45
	2.3.4.3 Double beam for warping or sizing	46
	2.3.4.4 Dividing the warp by semicircular disc	48

	2.3.4.5 Variable Separator Plates	49
	2.3.4.6 Dividable / Divisional Beams for creel efficiency	53
3	Concept of Designing and Prototyping	59
	3.1 Aim of the Work	60
	3.1.1 Problems related with Direct Warping	60
	3.1.2 Problems related with Sectional Warping	61
	3.1.3 Flow chart of the work done	61
	3.2 Designing a Manual Model	63
	3.3 Brief about NX Software	65
	3.4 3D Printing	67
	3.4.1 Working Principle of 3D printer	67
	3.4.2 Methods of 3D Printing	68
	3.4.2.1 Stereolithography (SLA)	68
	3.4.2.2 Digital Light Processing (DLP)	68
	3.4.2.3 Fused Deposition Modeling (FDM)	70
	3.4.2.4 Selective Laser Sintering (SLS)	70
	3.4.2.5 Selective Laser Melting (SLM)	70
	3.4.2.6 Electronic Beam Melting (EBM)	71
	3.4.2.7 Laminated Object Manufacturing (LOM)	71
	3.4.3 Features of Dimension SST 1200 es 3D Printer	73
	3.5 Design of the Model using NX software	75
	3.5.1 First Attempt	79
	3.5.1.1 Design of Outer Barrel	80
	3.5.1.2 Design of Inner Barrel	81
	3.5.1.3 Design of Flanges	83
	3.5.1.4 Design of Inner Fixed Flange	86
	3.5.1.5 Design of Separator Plates	87
	3.5.1.6 Design of Retainer Block	89

	3.5.1.7 Main Assembly	90
	3.5.1.8 3D Modelling	91
	3.5.1.8.1 3D Graphic Modelling	93
	3.5.1.8.2 Motion Simulation	93
	3.5.2 Second Attempt	94
	3.5.2.1 Design of Inner barrel	95
	3.5.2.2 Design of Separator Plate	96
	3.5.2.3 Full Assembly	96
	3.5.3 Third Attempt	97
	3.5.3.1 Design of Inner barrel	98
	3.5.3.2 Design of Separator Plate	
	3.5.3.3 Full Assembly	
4	Result and Discussion	100
	4.1 Introduction	101
	4.2 3D Prototype	101
	4.2.1 Parts – First Attempt	102
	4.2.2 Motion Simulation of Prototype – First Attempt	104
	4.2.3 Parts – Third Attempt	106
	4.2.4 Motion Simulation of Prototype – Third Attempt	107
	4.3 Measurements	109
	4.3.1 Measurements for Second Attempt	110
	4.3.2 Calculations for Second Attempt	115
	4.3.3 Measurements for Third Attempt	117
	4.3.4 Calculations for Third Attempt	118
5	Conclusions	119
	5.1 Major Outcomes	120
	5.2 Scope for Future Work	122
6	References	123
7	List of Publications	129