

Appendix - II

APPENDIX- II

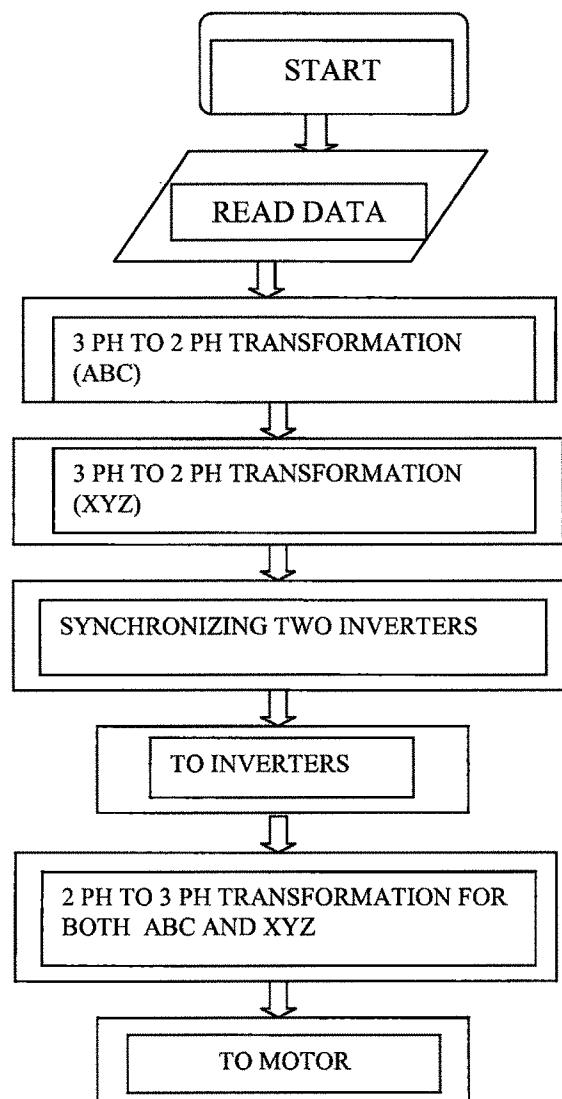
I] Matlab – software program in m-file for six phase Proto type Induction motor parameter:-

Editor - F:\Archana NanotyMulti_Multiphase_2622010.m*

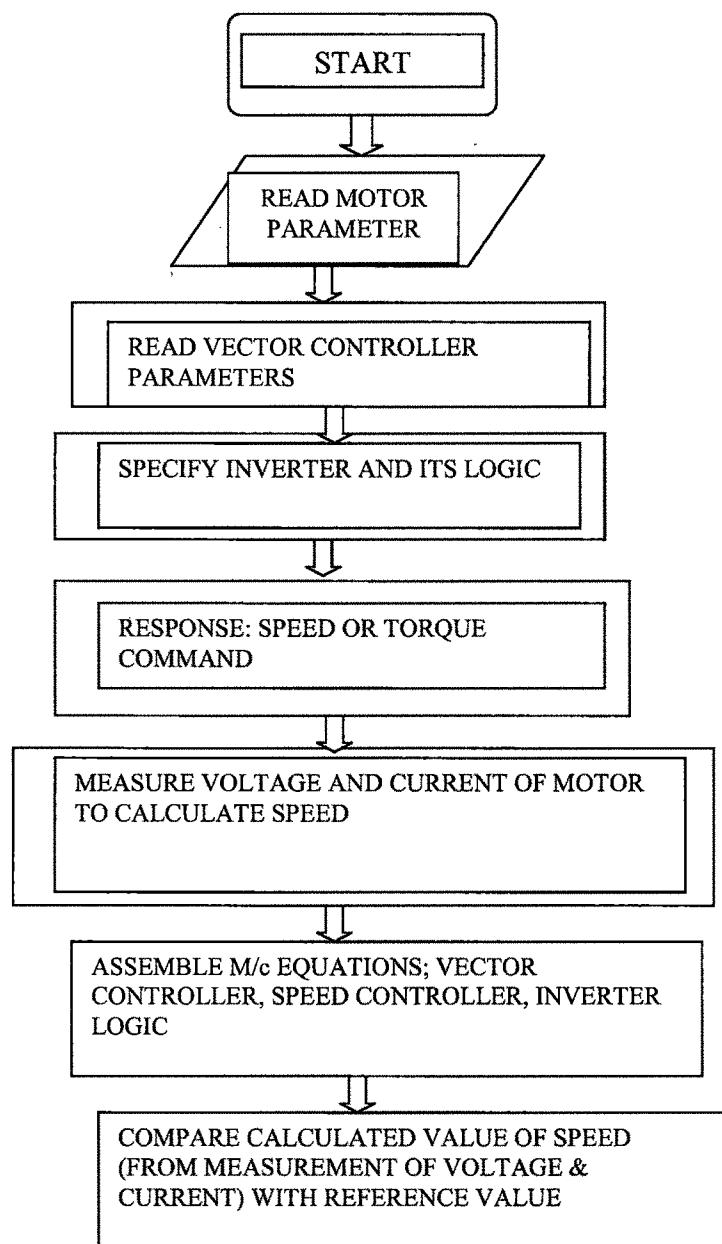
File Edit Text Go Cell Tools Debug Desktop Window Help

1 %Induction motor parameters
2 P= 3 hp
3 f= 50 Hz
4 no.of poles p=4
5 Vab=Vbc=Vca=200V
6 stator resistance (Rpb)= 1.7 Ohm
7 stator resistance (Rpb) r1= 1.7 Ohm
8 Stator leakage inductance per phase abc L11=0.0085H
9 Stator leakage inductance per phase abc L12=L13=0.0085H
10 Rotor resistance per phase rr = 0.56 Ohm
11 rotor leakage inductance per phase Lr=0.0085H
12 mutual leakage coupling between q and q axes of stator winding L1dq=0.0C
13 Common leakage inductance between two sets of stator winding L1m=0.001H
14 Mutual inductance Lm=0.11H
15 moment of inertia J=0.075 Kg m²
16 Te= 3Tm*(3/2)*(P/2)*(Lm/Lr)*(i1q1+i2q2)*lamdadrs-[id1+id2]*lamdaqr
17 lamdadrs=Llr*i1dr+Lm(id1+id2+i1dr)
18 lamdaqr=Llr*i1qr+Lm(i1q1+i2q2+i1qr)
19 wmp speed in radians per sec
20 p= d/dt
21 Te= Pm/wm
22 Vgs1= r1i1q1+w*lamdadrs1+p*lamdadrs1
23 Vds1= rs1ids1-w*lamdaqs1+p*lamdaqs1
24 Vgs2= r2i2q2+w*lamdadrs2+p*lamdadrs2
25 Vds2= rs2ids2-w*lamdaqs2+p*lamdaqs2
26 wmp= Te-TL/JS+B
27 wr= P/2 wmp
28
29

II] FLOW CHART FOR THREE PHASE TO TWO PHASE TRANSFORMATION



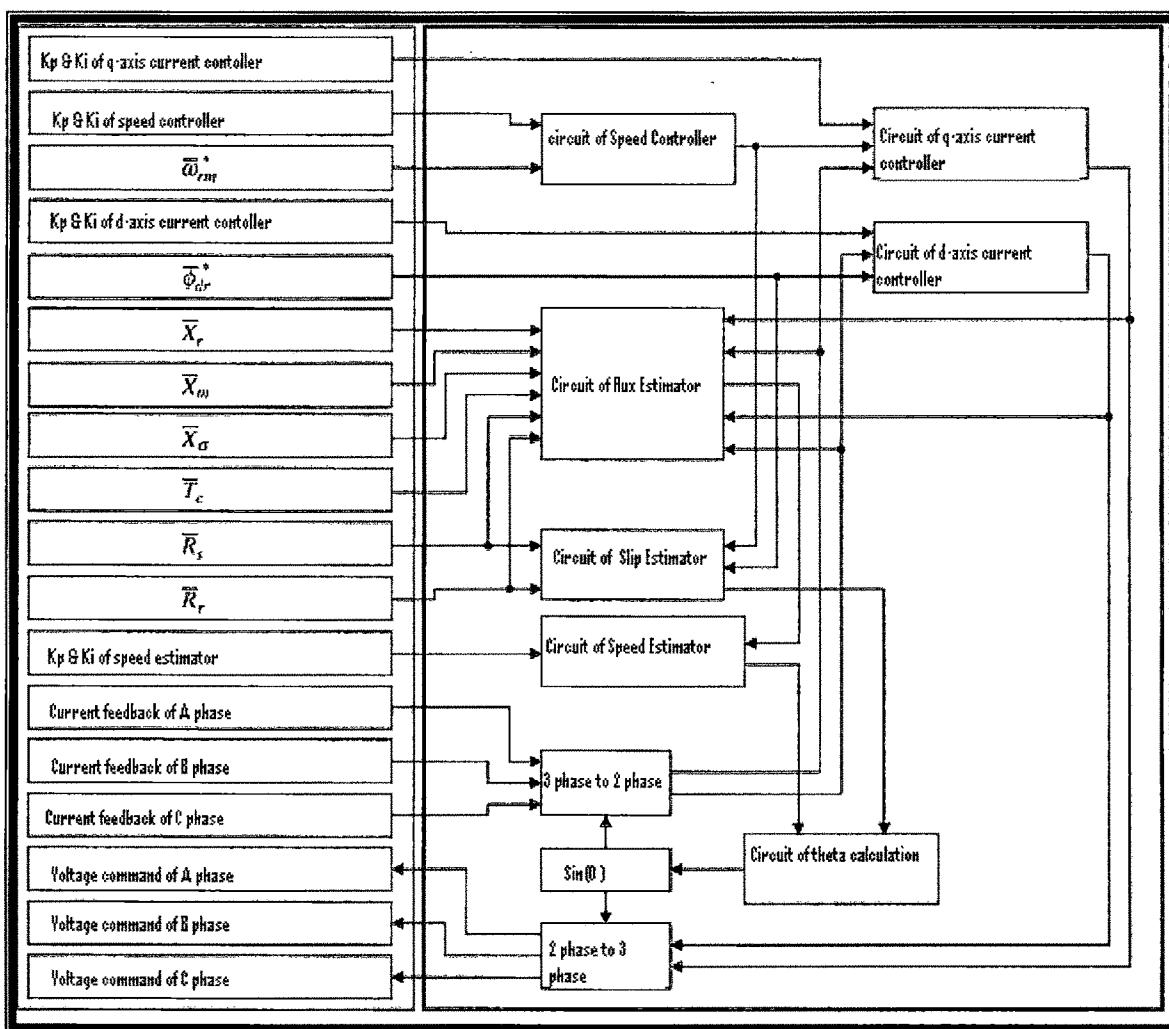
III] FLOW CHART FOR VECTOR CONTROL



IV] FPGA Implementation

A:-FPGA implementation of Sensor-less vector control

Algorithm (For three phase set ABC)

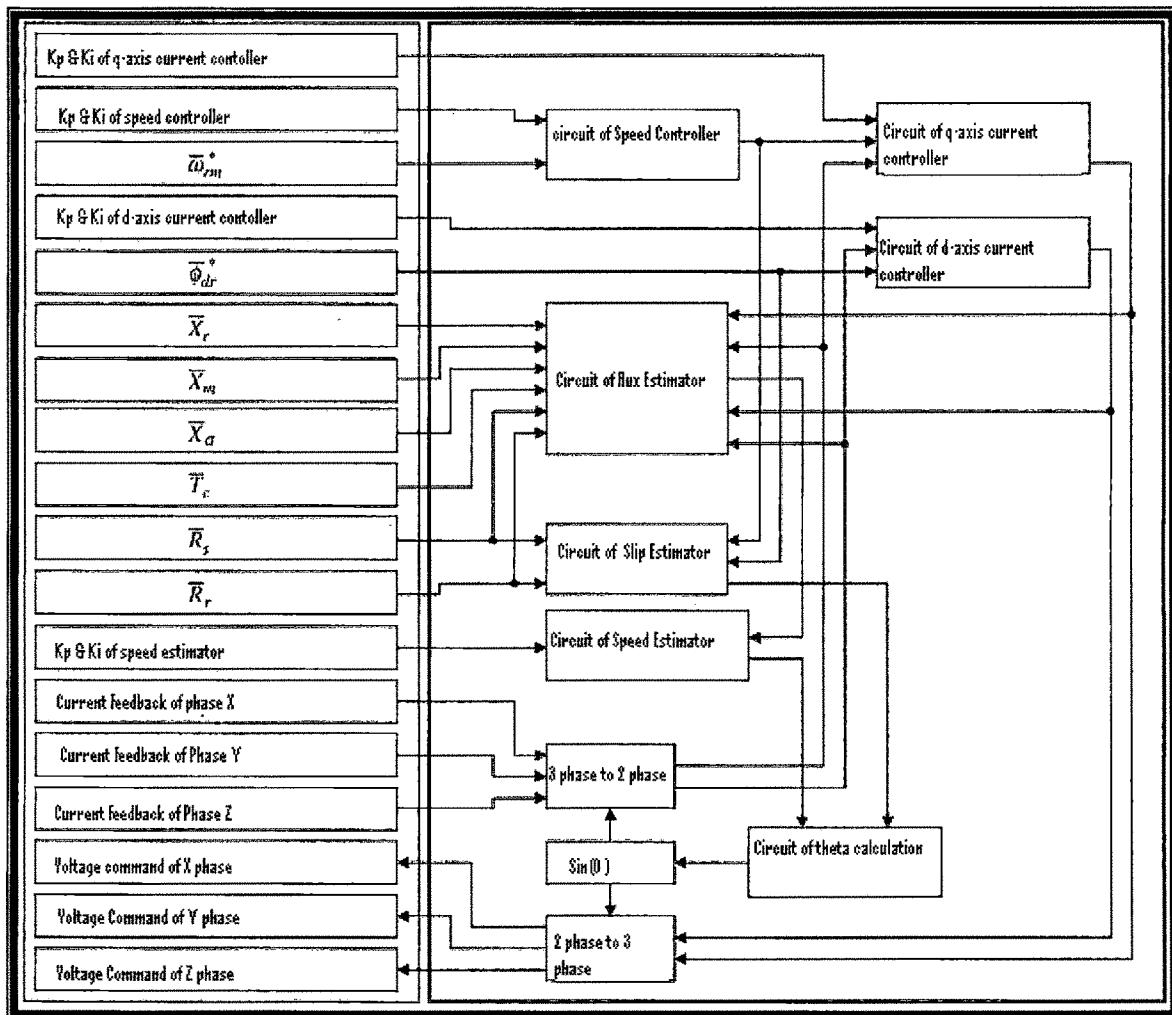


Interface between FPGA
and Microprocessor

FPGA Implementation

B:-FPGA implementation of Sensor-less vector control

Algorithm (For three phase set XYZ)



Interface between FPGA
and Microprocessor

FPGA Implementation