## NOMENCLATURE

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The following symbols are used frequently. Other symbols are defined in the text when they are first used.

a	ratio of max. film thickness to min. film thickness, h2/h1.
A	x-length of bearing/plate.
A <sub>mn</sub> , A <sub>mn</sub>	Fourier coefficients.
Ē	Magnetic induction field.
<sup>B</sup> O	applied magnetic field.
B <sub>mn</sub> , B <sub>mn</sub>	Fourier coefficients.
ć, c <sub>1</sub> , c <sub>2</sub>	magnetic parameters defined in the text.
c*	current parameter in the annular case.
c_1*	current parameter in the circular case.
$\vec{E} = (E_x, E_y, E_z)$	electric field vector.
Ēz	dimensionless z-component of the electric field.
F	frictional force.

Ŧ	dimensionless frictional force.
G <sub>mn</sub>	Fourier coefficients.
h	film thickness.
hl	min. film thickness in case of slider bearing and final film thickness in case of squeeze film bearing.
h <sub>2</sub>	max. film thickness.
ho	initial film thickness.
ħ	h/h <sub>l</sub> in case of slider bearing. h/h <sub>O</sub> in case of squeeze film bearing.
ĥ	dh/dt.
Н	thickness of the porous facing.
H <sub>l</sub> , H <sub>2</sub>	thickness of the lower and upper layers.
$\bar{H}$ , $\bar{H}_1$ , $\bar{H}_2$	dimensionless quantities $\frac{H}{A}$ , $\frac{H_{1}}{A}$ , $\frac{H_{2}}{A}$ .
Ż.	unit vector in x-direction.
I	total current.
$\vec{J} = (J_x, J_y, J_z)$	current density.
*10	unit vector in the y-direction.
k	unit vector in the z-direction.

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k, k <sub>l</sub> , k <sub>2</sub>	permeabilities.
L, L <sub>l</sub> , L <sub>2</sub>	defined in 2.(7).
m*	porosity.
M	Hartmann number.
M	max. Hartmann number.
p .	fluid pressure in the film region.
P, P <sub>1</sub> , P <sub>2</sub>	fluid pressures in the porous regions.
P.	dimensionless fluid pressure in the film region.
p <sub>O</sub>	some fixed pressure.
$\vec{q} = (u, v, w)$	fluid velocity in the film region.
Q,Q <sub>1</sub> ,Q <sub>2</sub> ,Q <sub>3</sub> ,Q <sub>4</sub> ,Q <sub>5</sub>	constants, of integration.
r	radial space coordinate.
r_l	outside radius of disks.
r <sup>2</sup> 2	inside radius of disks.
S	magnetic field step location.
t .	time.
Δt	response time.

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$\Delta$ T	dimensionless response time.
T, T <sub>1</sub> , T <sub>2</sub>	defined in 2.(7).
u	x-component of the fluid velocity in the film region.
U	x-component of the velocity of the upper surface.
<sup>u</sup> 0	slip velocity in the x-direction.
V	y-component of fluid velocity in the film region.
v <sub>h</sub> , v <sub>0</sub>	values of v at $y = h$ , 0 respectively.
v <sub>h</sub>	normal velocity of the upper surface.
$\vec{v} = (v_x, v_y, v_z)$	fluid velocity in the lower porcus region.
$\vec{v}_0 = (v_{0x}, v_{0y}, v_{0z})$	value of $\vec{v}$ when $y = 0$ .
$\vec{v}^* = (v_x^*, v_y^*, v_z^*)$	fluid velocity in the upper porous region.
W	z-component of the fluid velocity in the film region.
w <sub>O</sub>	slip velocity in the z-direction.
W	load capacity.
W	dimensionless load capacity.

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x	coordinate along the film.
x	dimensionless quantity $x/A_{\bullet}$
Ŧ	x-coordinate of the centre of pressure.
У	coordinate across the film or axial coordinate.
Z	coordinate perpendicular to xy-plane.
α	$(12 \psi)^{1/3}$
α <sub>O</sub>	central film thickness.
ά <sub>0</sub>	āα <sub>0</sub> /dt.
α <sub>01</sub> , α <sub>02</sub>	initial and final values of $\alpha_0$ .
β	curvature of the upper plate.
β	curvature parameter, $\beta r_1^2$ .
δ <sub>ℓ1</sub>	Kronecker delta.
μ	viscosity of fluid.
$\mu_{e}$	magnetic permeability of fluid.
P	fluid density.

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σ-	fluid conductivity.
$\psi, \psi_1, \psi^*, \psi_0$	permeability parameters.
<u>_</u>	velocity of rotation of lower

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